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Scorley@everest.srd.bt.co.uk 3 KPN Research, P. O. Box 15000 ,9700 CD Groningen, The Netherlands.
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Conflict-Based Search For Optimal Multi-Agent Path Finding

At The Same Time) While Minimizing A Cumulative Cost Func-tion. The Common Cost Function Is The Sum Over All Agents Of The Number Of Time Steps Required To Reach The Goal Location. Therefore, Both Move And Wait Actions Cost 1.0. MAPF Has Practical Applications In Robotics, Video Games, Ve Jul 1th, 2024

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