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## **Chapter 9 Matrices And Transformations 9 MATRICES AND ...**

Chapter 9 Matrices And Transformations 236 Addition And Subtraction Of Matrices Is Defined Only For Matrices Of Equal Order; The Sum (difference) Of Matrices A And B Is The Matrix Obtained By Adding (subtracting) The Elements In Corresponding Positions Of A And B. Thus  $A = \begin{pmatrix} 1 & 2 & 3 \\ -1 & 0 & -1 \end{pmatrix}$  And  $B = \begin{pmatrix} -1 & 2 & 4 \\ -3 & -3 & -3 \end{pmatrix} \Rightarrow A+B = \begin{pmatrix} 0 & 4 & 7 \\ -4 & -3 & -4 \end{pmatrix}$  Jun 1th, 2024

## **Similar Matrices And Diagonalizable Matrices**

$\begin{pmatrix} 1 & 0 & -5 & 0 & 0 & 3 \\ 1 & 0 & 0 & -5 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 2 & 5 & 0 & 0 \\ 9 & 0 & 0 & 0 & 1 & 0 \end{pmatrix} B^3 = I$   $B^2 \neq I$   $B = \begin{pmatrix} 1 & 0 & 2 & 5 & 0 & 0 \\ 0 & -5 & 0 & 0 & 3 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & -12 & 5 & 0 \\ 0 & 0 & 0 & 0 & 2 & 7 \end{pmatrix}$  And In General  $B^k = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & (-5)^k & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$  . This Example Illustrates The General Idea: If B Is Any Diagonal Matrix And K Is Any Positive Integer, Then  $B^k$  Is Also A Diagonal Matrix And Each Diagonal Jun 4th, 2024

## **Population And Transition Matrices Stationary Matrices And ...**

X9.2 Theorem 1 Let P Be The Transition Matrix For A Regular Markov Chain. 1 There Is A Unique Stationary Matrix S That Can Be Found By Solving The Equation  $SP = S$ . (shortcut: Take Transposes And Row-reduce The  $(n + 1) \times n$  Matrix  $P^T - I$  ) 2 Given Any Initial-state Matrix  $S_0$ , The State Matrix May 3th, 2024

## **Sage 9.2 Reference Manual: Matrices And Spaces Of Matrices**

22 Dense Matrices Over The Real Double Field Using NumPy435 23 Dense Matrices Over  $GF(2)$  Using The M4RI Library437 24 Dense Matrices Over  $F_2$  For  $2 \leq n \leq 16$  Using The M4RIE Library447 25 Dense Matrices Over  $Z/nZ$  For