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Multi-Finger Haptic Rendering Of Deformable Objects(3)  $E E L E E V V F R V R R R R_2 = -\pi^2 \rho$  (4)  $FC F_b F_d F_f R R R R = + +$  (5)  $FG$ : Gravity (me Is The Mass Of E And G Is The Gravity Acceleration);  $FL$ : Ambient Viscous Friction ( $r$  Is The Radius,  $\rho$  Is The Medium Density And  $V$  Is The Velocity);  $FC$ : Connection Forces, See Eq. 6.  $FC F_b F_d F_f R R$  May 2th, 2024 LITIS SIMULATIO 8ª EDICIÓN - CURSO 2019/2020 BASE Haya Previsto Y Dejar Para Las Refutaciones Posteriores Responder Los Que No Haya Previsto. Esto Puede Ser Un Motivo Para Pedir Al Juez (y Que éste Lo Conceda) Más Turnos En La Fase De Réplica. En Este Sentido, La Posición Del Demandado Exige Más Reflejos Y Una Preparación Más Flexible, Jun 3th, 2024 11 AM LAD 2 Ample Silo Simulatio Emonstratin Continuous ... Ample Silo Simulatio Emonstratin Continuous Mode Of O Eratio Stop(NC) Start 0) Run Ght So Eno D Valve (END) He Boxis NOT In The Fill Area, Run Aht Lev Run \_l\_ight S Tch The Ful Sor ProxSWltch Proxswltch . Feb 4th, 2024.

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