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The Speed Of Light C= 1. Greek Indices ( $\mu$ ,  $\nu$ , Etc., Which Take The Range {0,1,2,3}) Will Be Used To Represent Components Of Tensors. The Einstein Summation Convention Is Assumed: Repeated Upper And Lower Indices Are To Be Summed Over Their Ranges, E.g., A $\mu$ B  $\mu$  = A0B0 + A1B1 + A2B2 + A3B3. Fourvectors Will Be Represented With Jan 1th, 2024

#### PART 1: INTRODUCTION TO TENSOR CALCULUS

PART 1: INTRODUCTION TO TENSOR CALCULUS A Scalar Eld Describes A One-to-one Correspondence Between A Single Scalar Number And A Point. An N-dimensional Vector Eld Is Described By A One-to-one Correspondence Between N-numbers And A Point. Let Us Generalize These Concepts By Assigning N-squared Numbers To A Single Point Or N-cubed Numbers To A Single May 1th, 2024

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Manifolds Generally Speaking, Amanifoldis A Space That With Curvature And Complicated Topology That Locallylooks Like Rn. Examples: Rn Itself. R Is A Line And R2 A Plane. The N-sphere, Sn; That Is, The Locus Of All Points Some fixed Distance From The Origin In Rn+ 1.S Is A Circle And S2 Sphere. The N-torus Tn.T2 Is The Surface Of A Doughnut. A Riemann Surface Of Genus G. Mar 3th, 2024

#### INTRODUCTION TO THE ESSENTIALS OF TENSOR CALCULUS

Summation Convention Of Tensor Calculus: Each Repeated Index In An Expression, Here J, Is To Be Summed From 1 To N. The Relation Above Gives A Prescription For Transforming The (contravariant) Vector Dxi To Another System. This Establishes The Rule For Transforming Any Contravariant Vector From One System To Another. Ai  $(q) = (\partial q \mid \partial xj) Aj(x) Jan 3th, 2024$ 

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